

Lecture 2 . Morse homology and Floer homology.

Additional bibliography: F. Laudenbach, Symplectic geometry and Floer homology, *Eusaios Matematicos* 7 (2004), 1-50

§1. Compactness and gluing in Morse theory.

N finite dim. mfd, $f: N \rightarrow \mathbb{R}$ proper Morse function, g Riemannian metric

s.t. (f, g) satisfies the Morse-Smale condition:

$$\forall p, q \in \text{Cut}(f), \quad W^u(p) \pitchfork W^s(q) \quad (\text{generic condition in } H)$$

Notation: $\begin{aligned} \hat{M}(p, q) &= W^u(p) \cap W^s(q) \\ M(p, q) &= W^u(p) \cap W^s(q) / \mathbb{R} \\ |p| &= \text{ind}(p) \end{aligned}$

space of Riemannian metrics

$\left\{ \begin{array}{l} \text{empty if } |p| < |q| \\ \text{point if } |p| = |q|, \text{ i.e. } p = q \\ \text{dive} = |p| - |q| \text{ if } |p| > |q| \\ \text{and if nonempty} \end{array} \right.$

Theorem (compactness): Given $p, q \in \text{Cut}(f)$ and a sequence $[\gamma_n] \in \hat{M}(p, q)$, $n \geq 1$

there exist points $x^0, x^1, \dots, x^l \in \text{Cut}(f)$, $x^0 = p$, $x^l = q$

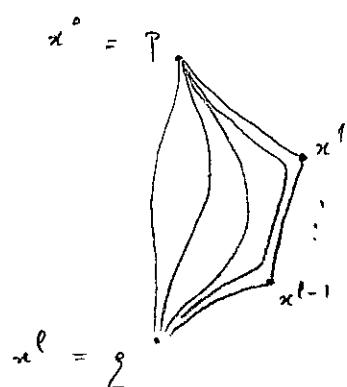
trajectories $[\gamma_i] \in \hat{M}(x^{i-1}, x^i)$, $i = 1, \dots, l$

subsequence $[\gamma_{n_k}] \subset [\gamma_n]$

such that $[\gamma_{n_k}]$ converges to the "broken trajectory" $([\gamma_1], \dots, [\gamma_l])$ in the following sense:

$\forall i = 1, \dots, l$, \exists "shifts" $s_{n_k}^i$ such that

$\gamma_{n_k}(\cdot + s_{n_k}^i) \longrightarrow \gamma_i$ uniformly on compact sets, together with all derivatives.



Crucial ingredient in the proof is the following :

Lemma : Any sequence γ_n of gradient trajectories running from p to q has a subsequence which converges uniformly on compact sets with all derivatives to a gradient trajectory $\gamma : \mathbb{R} \rightarrow N$.

Proof : Since $\dot{\gamma}_n = -\nabla f(\gamma_n)$ and $\text{im}(\gamma_n) \subset f^{-1}([f(q), f(p)])$ compact.

Step 1. $\Rightarrow \dot{\gamma}_n$ uniformly bounded

Thus $\dot{\gamma}_n$ is an equicontinuous & bounded family

By Arzela - Ascoli : \exists subsequence, still denoted γ_n , converging wif. cpt. sets.
to $\gamma : \mathbb{R} \rightarrow N$.

Step 2. We now show that γ is a gradient trajectory.

Since $\dot{\gamma}_n = -\nabla f(\gamma_n) \rightsquigarrow \dot{\gamma}_n$ converges wif. cpt sets to vector field v along γ
that satisfies $v = -\nabla f(\gamma)$.

But $\gamma_n \rightarrow \gamma$ in distributional sense, hence $\dot{\gamma} = -\nabla f(\gamma)$ □

Idea of proof of cptness theorem : once we have obtained a limit γ , if its

endpoint $\gamma(-\infty)$ is different from p , we shift so that $f(\gamma_n(.-+s_n)|_{s=0}) > f(\gamma(-\infty))$

& apply lemma again. Conclude inductively. □

Highlight #4 : Proof of compactness theorem in Morse theory.

Corollary : If $|p| - |q| = 1$, $\mathcal{M}(p, q)$ is a compact 0-dim. mfd, hence
a finite set.

Question: What about $M(p, q)$ if $|p| - |q| = 2$?

We know it is a 1-dimensional manifold, hence each component is either a circle or an open interval.

Theorem (gluing) There is a 1:1 bijective correspondence between the noncompact ends of $M(p, q)$ and

$$\bigsqcup_{\begin{array}{l} |n|=|p|-1 \\ =|q|+1 \end{array}} M(p, n) \times M(n, q)$$

Rephrasing: There exists "gluing map" defined for $R_0 > 0$ large enough

$$\# : \bigsqcup_n M(p, n) \times M(n, q) \times [R_0, \infty] \longrightarrow M(p, q)$$

such that:

- i) $\#$ is diffeomorphism onto its image
- ii) the complement of the image has compact closure
- iii) $\#([x], [x'], R) \longrightarrow ([x], [x'])$ as $R \rightarrow \infty$
convergence to broken trajectory in previous sense.

Remark: We can write the gluing theorem in a more appealing way as

$$D M(p, q) = \bigsqcup_{\begin{array}{l} |n|=|p|-1 \\ =|q|+1 \end{array}} M(p, n) \times M(n, q)$$

In the case $|p| - |q| > 2$, the analogous statement is

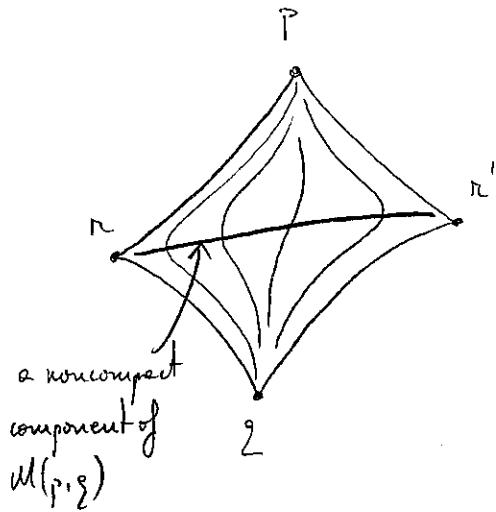
$$D M(p, q) = \bigsqcup_{x^1, \dots, x^{l-1}} M(p, x^1) \times M(x^1, x^2) \times \dots \times M(x^{l-1}, q)$$

Exercise: State a mathematically rigorous gluing theorem for the case $|p| - |q| > 2$.

Exercise: Test your understanding of the gluing theorem for Floer trajectories (cf. Highlight #8) by proving the gluing theorem for Morse gradient trajectories.

Consequence of compactness and gluing: ∂ is well-defined and $\partial^2 = 0$.

$$\begin{aligned}\partial^2(p) &= \partial \left(\sum_{|\alpha|=|p|-1} \#_{\text{alg}} M(p,\alpha) \alpha \right) = \sum_{|\alpha|=|p|-1} \#_{\text{alg}} M(p,\alpha) \sum_{|\beta|=|\alpha|-1} \#_{\text{alg}} M(\alpha,\beta) \beta \\ &= \sum_{|\beta|=|p|-2} \left[\sum_{\substack{|\alpha|=|p|-1 \\ |\beta|=|\alpha|-1 \\ =|\beta|+1}} \#_{\text{alg}} M(p,\alpha) \cdot \#_{\text{alg}} M(\alpha,\beta) \right] \beta \\ &= \sum_{|\beta|=|p|-2} \left(\sum_{\substack{|\alpha|=|p|-1 \\ (\alpha', \beta') \\ =|\beta|+1 \\ \in M(p,\alpha) \times M(\alpha,\beta)}} \varepsilon([\alpha]) \cdot \varepsilon([\beta']) \right) \beta.\end{aligned}$$



Now each pair $([\alpha], [\beta'])$ corresponds to a noncompact end of $M(p,g)$.

The latter is oriented, and each of its two boundary components inherits an orientation i.e. a sign (in dimension 0).

Exercise: This sign equals $\varepsilon([\alpha]) \cdot \varepsilon([\beta'])$.

Consequence: In the sum $\sum \varepsilon([\alpha]) \cdot \varepsilon([\beta'])$ the terms cancel two-by-two,

so that $\partial^2 = 0$

■■■

§2. Floer theory

(M, ω) symplectically aspherical manifold.

- $\langle \omega, \bar{u}_2 \rangle = 0$
 - excludes holomorphic spheres
 - allows to define action functional on LM , without going to a cover

- $\langle c_1, \bar{u}_2 \rangle = 0$
 - allows for \mathbb{Z} -grading

More generally: Floer homology (Hamiltonian version) can be defined

... with ... over \mathbb{Z} for monotone symplectic mfd's

$$c_1 = \lambda \omega, \quad \lambda > 0$$

- over \mathbb{Q} for arbitrary symplectic mfd's
- with coeff. in a fancy coefficient ring (Novikov ring) to account for the presence of holomorphic spheres

$$H : S^1 \times M \longrightarrow \mathbb{R} \quad \text{"Hamiltonian"}$$

X_H^t time dependent Hamiltonian vector field, defined by $\omega(X_{Ht}^t) = dH_t$

$$\mathcal{A}_H : LM \longrightarrow \mathbb{R}, \quad \mathcal{A}_H(\gamma) = - \int_{D^2} \bar{\gamma}^* \omega - \int_{S^1} H(t, \gamma(t)) dt$$

(contractible loops in M)

with $\bar{\gamma} : D^2 \longrightarrow M$ smooth extension of γ to the disc.

Note: $\langle \omega, \bar{u}_2 \rangle = 0$ ensures that \mathcal{A}_H is well-defined, indep. of choice of $\bar{\gamma}$.

$$\text{Crit}(\mathcal{A}_H) \stackrel{\text{not.}}{=} \mathcal{P}(H) = 1\text{-periodic orbits of } H$$

Standing assumption : All 1-periodic orbits of H are nondegenerate, meaning that the linearized time 1 flow has no eigenvalues = 1.

$$\forall \gamma \in S(H), \det((\varphi_H^1)_*(\gamma(0)) - \text{Id}) \neq 0.$$

Exercise : (i) this is a generic condition in the space of all Hamiltonians.

(ii) it is equivalent to d_{H_1} being Morse (see lecture 3)

(iii) if H is time-independent, the condition is never satisfied along a non-constant 1-periodic orbit.

(iv) if H is time-independent and C^2 -small, then it has only constant 1-per. orbits and the condition is equivalent to H being Morse

Almost complex structure $J_t, t \in S^1$ on M , compatible with ω

~ induces L^2 -metric on $\mathcal{L}M$:

$$\xi, \gamma \in \Gamma(\gamma^* TM) = T_\gamma \mathcal{L}M$$

$$\langle \xi, \gamma \rangle := \int_{S^1} \omega(\dot{\gamma}(t), J_t(\gamma(t)) \cdot \dot{\gamma}(t)) dt.$$

Differential of d_H is

$$dd_H(\gamma) \cdot \xi = \int_{S^1} \omega(\dot{\gamma} - X_H^t(\gamma(t)), \xi(t)) dt$$

L^2 -gradient vector field of d_H is

$$\nabla d_H(\gamma) = \overline{J}_t(\gamma(t)) \cdot (\dot{\gamma}(t) - X_H^t(\gamma(t)))$$

Equation of negative gradient lines $u: \mathbb{R} \rightarrow \mathcal{Z}_0 M \equiv u: \mathbb{R} \times S^1 \rightarrow M$

$$\boxed{\partial_s u + J_t(u) (\partial_t u - X_H^t(u)) = 0}$$

Floer's equation

merely a mixture between

- the Cauchy-Riemann equation ($H=0$)
- the usual gradient line equation
(H, J, u independent of t)

Note: With my conventions $JX_H = \nabla H$, so that in the case where H, J, u are independent of t the equation is $\partial_s u = \nabla H(u)$, positive gradient lines

Remark: Consider the case $M = \mathbb{C}^n$, $J = i$, $H = 0$.

i) Floer's equation becomes $\partial_s u + i \partial_t u = 0$, i.e. u is holomorphic. In particular $u(s, \cdot)$ is analytic.

Thus the L^2 -flow of $\partial_t u$ is ill-defined on $\mathcal{Z}_0 M$!

ii) Given loop $\gamma = \sum_{k \in \mathbb{Z}} z_k e^{ikt}$, its action is $\int \gamma dy = \pi \sum_{k \in \mathbb{Z}} k |z_k|^2$.

This quadratic form has infinite-dimensional positive and negative eigenspaces \rightarrow even if the flow were defined, the index of a critical point would be infinite, hence Morse theory would not apply.

Floer's idea: L^2 -gradient trajectories that connect critical points of J_H come in finite-dimensional families and capture topology.

Definition : Given $x, y \in \mathcal{P}(H)$, denote

$$\hat{\mathcal{M}}(x, y) = \left\{ u : \mathbb{R} \times S^1 \longrightarrow M : \bar{\partial}_{J, H} u = 0, u(-\infty, \cdot) = x \right. \\ \left. u(+\infty, \cdot) = y \right\}$$

$\mathcal{M}(x, y) = \hat{\mathcal{M}}(x, y)/_{\mathbb{R}}$ if $x \neq y$. "moduli space of Floer trajectories"

Definition : $FC = FC(H, J) = \bigoplus_{x \in \mathcal{P}(H)} \mathbb{Z} < x >$

$$\partial : FC \longrightarrow FC$$

$$\partial x = \sum_y \#_{alg} \mathcal{M}(x, y) \cdot y \quad "Floer complex".$$

$\dim \mathcal{M}(x, y) = 0$

↑ this is made possible by a
"choice of coherent orientations".

Theorem (Floer) Assume M is closed and $\langle [\omega], \pi_2(M) \rangle = 0$. Then:

[Definition]

- ∂ is well-defined for a generic choice of $J = (J_t)$
- $\partial^2 = 0$
- $FH(H, J)$ is independent of the choice of H and J .

More precisely : a generic homotopy $(H_0, J_0) \rightarrow (H_1, J_1)$ induces a
"continuation isomorphism" $\tau : FH(H_0, J_0) \rightarrow FH(H_1, J_1)$

and the latter is independent of the choice of homotopy.

Theorem (Floer) : Some assumptions. We have

[Computation]

$$FH(H, J) \cong H(M)$$

singular cohomology

We explain Theorem - Definition and Theorem - Computation in lectures 3 & 4.

Highlight #3. Compactness theorem for gradient trajectories in Morse theory

Setup: $f: M \rightarrow \mathbb{R}$ proper Morse function, g Ricci metric, M finite dim. mfld

$$M(p, g) = W^u(p) \cap W^s(g) / \mathbb{R}$$

Theorem: Let $p, q \in \text{Crit}(f)$ and $[\gamma_n] \in M(p, q)$. There exist

- points $x^0 = p, x^1, \dots, x^\ell = q \in \text{Crit}(f)$

- trajectories $[\gamma_i] \in M(x^i, x^{i+1})$, $i=0, \dots, \ell$

- subsequence $[\gamma_{n_k}] \subset [\gamma_n]$

s.t. $\forall i=0, \dots, \ell$, \exists shifts $s_{n_k}^i$ s.t. $\gamma_{n_k}^i (+ s_{n_k}^i) \rightarrow \gamma_i$ uniformly on cpt sets
together with all derivatives
 (C_{loc}^∞)

Lemma: The sequence γ_n has a subsequence that converges in C_{loc}^∞ to a gradient traj. γ .

Proof (already seen in lecture 2)

- f proper $\Rightarrow M(\gamma_n) \subset f^{-1}([f(q), f(p)])$ compact

- $\dot{\gamma}_n = -\nabla f(\gamma_n)$ and ∇f bdd on cpt sets $\Rightarrow \dot{\gamma}_n$ unif. bdd

The conclusion then follows from the Arzela - Ascoli theorem.

(which is the basis of all compactness theorems for function spaces).

Note: convergence of derivatives is formal consequence of the equation $\dot{\gamma} = -\nabla f(\gamma)$. □

Proof of the theorem

Step 1 (exercise): Let $\gamma_n \xrightarrow{C_{loc}^\infty} \gamma$ with $\gamma_n \in \hat{M}(p, q)$ and $\gamma \in \hat{M}(x, y)$. Then

$$f(p) \geq f(x) \geq f(y) \geq f(q)$$

Step 2: Assume $f(p) = f(x)$. Then $p = x$. Similarly, if $f(y) = f(q)$ then $y = q$. It is of course enough to prove the first assertion. Assume by contradiction $p \neq x$.

Fix disjoint balls B_p, B_x around p and x which do not contain other critical points than p and x . By possibly shrinking B_p we can assume w.l.o.g. that $M \cap B_p = \emptyset$.



Let $s_n = \inf_s \gamma_n(s) \in \partial B_p$ ($\gamma_n(s)$ finite, since $\gamma_n(s) \in \text{int } B_p$ for $s < 0$).

The sequence $\gamma_n(\cdot + s_n)$ has convergent subsequence in C_{loc}^∞ to $\tilde{\gamma} \in \mathcal{M}(\tilde{x}, \tilde{y})$.

Claim: $\forall \varepsilon, \exists n(\varepsilon), \forall n \geq n(\varepsilon), f(p) \geq f(\gamma_n(s_n)) \geq f(x) - \varepsilon$.
This is automatic, since $\gamma_n(-\infty) = p$.

Fix $\varepsilon > 0$. Choose σ s.t. $f(x) - f(\gamma(\sigma)) < \frac{\varepsilon}{2}$ and $\gamma(\sigma) \in B_x$.

Since $\gamma_n(\sigma) \rightarrow \gamma(\sigma)$, $\exists n(\varepsilon), \forall n \geq n(\varepsilon), \gamma_n(\sigma) \in B_x$ and
 $f(\gamma(\sigma)) - f(\gamma_n(\sigma)) < \frac{\varepsilon}{2}$.

Thus $f(x) - f(\gamma_n(\sigma)) < \varepsilon$, i.e. $f(\gamma_n(\sigma)) > f(x) - \varepsilon$.

But our defi. of s_n ensures $f(\gamma_n(s_n)) > f(\gamma_n(\sigma))$.

This proves the claim.

Passing to the limit $n \rightarrow \infty$ we obtain

$$\forall \varepsilon, f(p) \geq f(\tilde{\gamma}(0)) \geq f(x) - \varepsilon \stackrel{\text{assumption}}{=} f(p) - \varepsilon.$$

Thus

$f(p) \geq f(\tilde{x}) \geq f(\tilde{\gamma}(0)) = f(p)$, which implies that

$\tilde{\gamma}$ is a constant trajectory — a contradiction with $\tilde{\gamma}(0) \in \partial B_p$,
which is disjoint from $\text{Cut}(f)$. \square

Highlight #4 (continued)

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Step 3 : Let us fix $\varepsilon > 0$ s.t. $[f(p) - \varepsilon, f(p)]$ is regular interval
and choose s_n^1 s.t. $f(\gamma_n(s_n^1)) = f(p) - \varepsilon$.

By Lemma, Step 1, and Step 2 we get subsequence $\gamma_{n_k}^1$ s.t.

$$\gamma_{n_k}^1(\cdot + s_{n_k}^1) \xrightarrow{C_{loc}^\infty} \gamma^1 \in \hat{\mathcal{M}}(p, \alpha^1).$$

If $\alpha^1 = q$, we are done

If not, we have $f(\alpha^1) > f(q)$ by Step 2. We repeat this same procedure with $\varepsilon > 0$ chosen such that $[f(\alpha_1) - \varepsilon, f(\alpha_1)]$ is regular interval,
and s_n^2 s.t. $f(\gamma_n(s_n^2)) = f(\alpha_1) - \varepsilon$.

We continue inductively. The process is finite since the interval $[f(q), f(p)]$ contains a finite number of critical values.

□

